



SELECTING THE BEST IDLER SIZE

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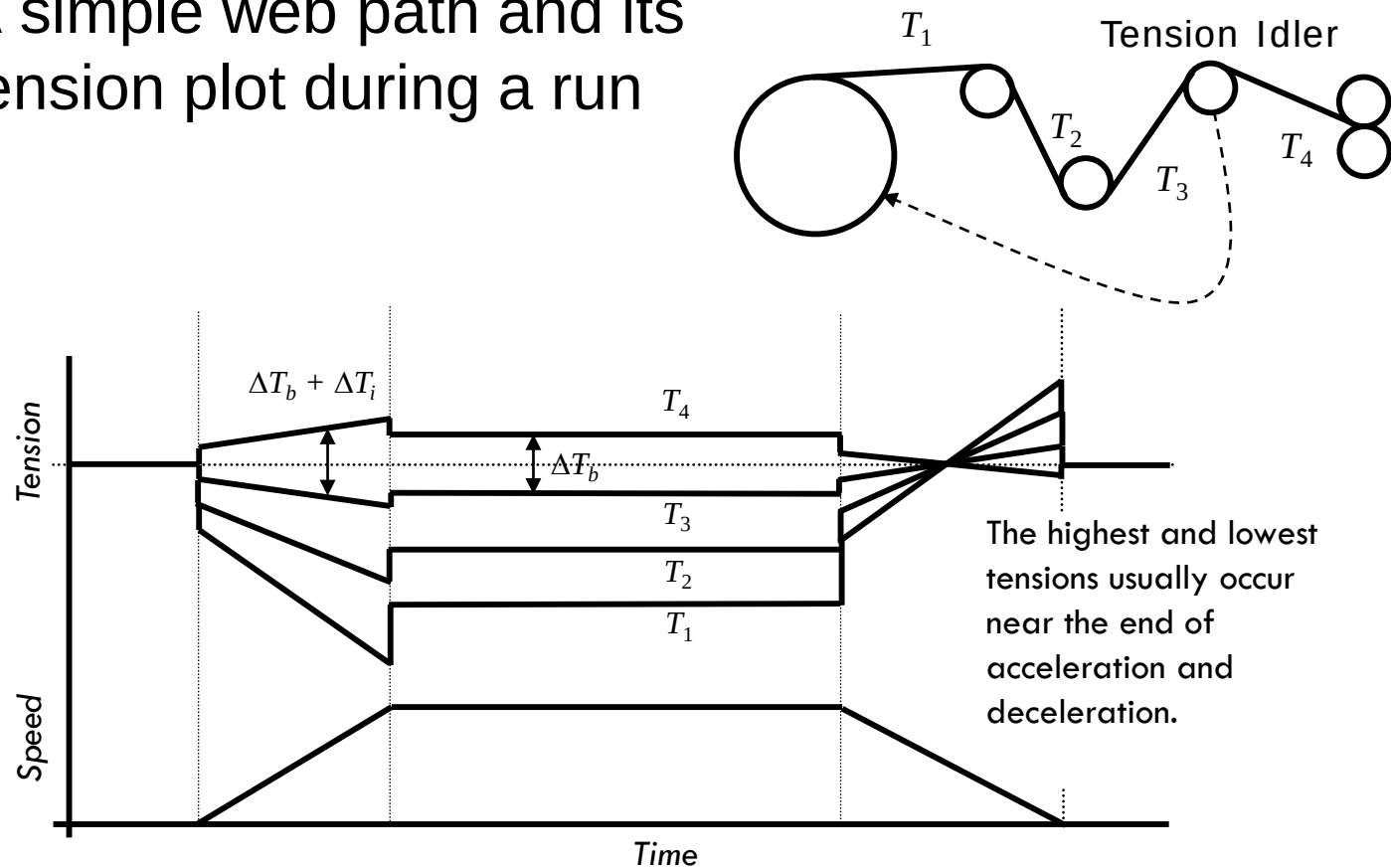


WHY IDLERS MATTER

- Idlers influence the highest and lowest tension we can run in a web path.
- Idler bearing drag and inertia upset tension during acceleration and deceleration.
- Idlers can defeat the most sophisticated tension control systems.
- Idler diameter affects a lot of things.

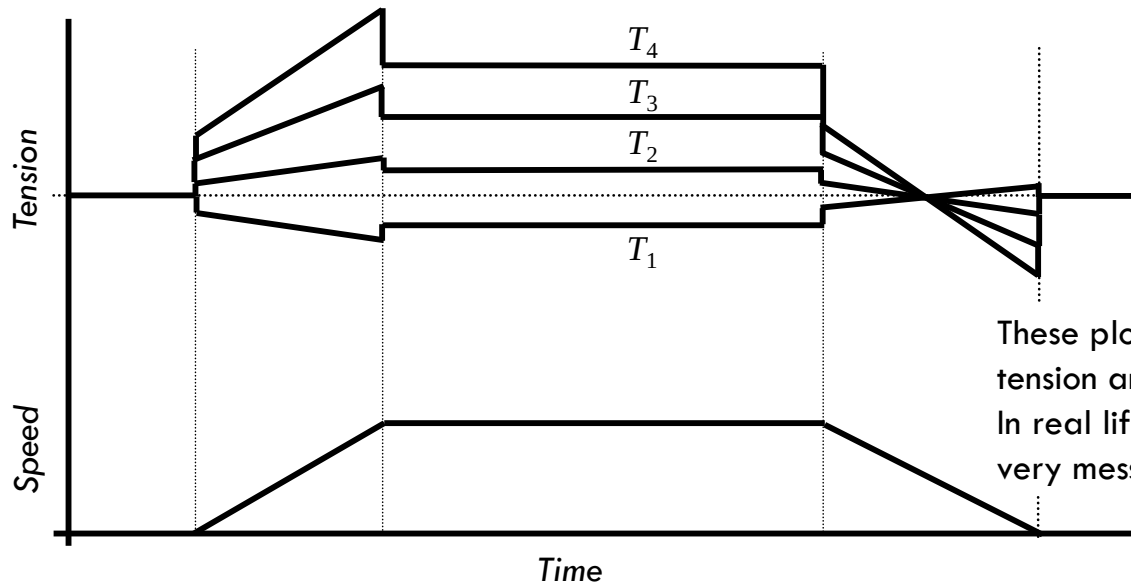
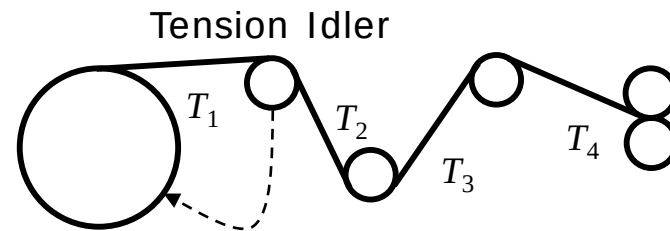
HOW IDLERS AFFECT TENSION

- A simple web path and its tension plot during a run



HOW IDLERS AFFECT TENSION

- The location of the tension idler matters.



These plots assume perfect tension and drive control. In real life they can be very messy.

BEARING DRAG

- A simple bearing torque formula

$$\textit{Torque.bearing} = \tau + \gamma\omega$$

- Restated in terms of radius and tension difference across the idler, the bearing drag force is

$$\Delta T_b = \tau/r_o + \gamma V/r_o^2$$

INERTIAL DRAG

- A simple formula for inertial torque

$$\text{Torque.ineria} = J\alpha \text{ where } J = mr_o^2$$

- Restated in terms of radius and tension difference, the inertial drag is

$$\Delta T_i = mA$$

- Calculating the mass from wall thickness, length and density, the tension difference is

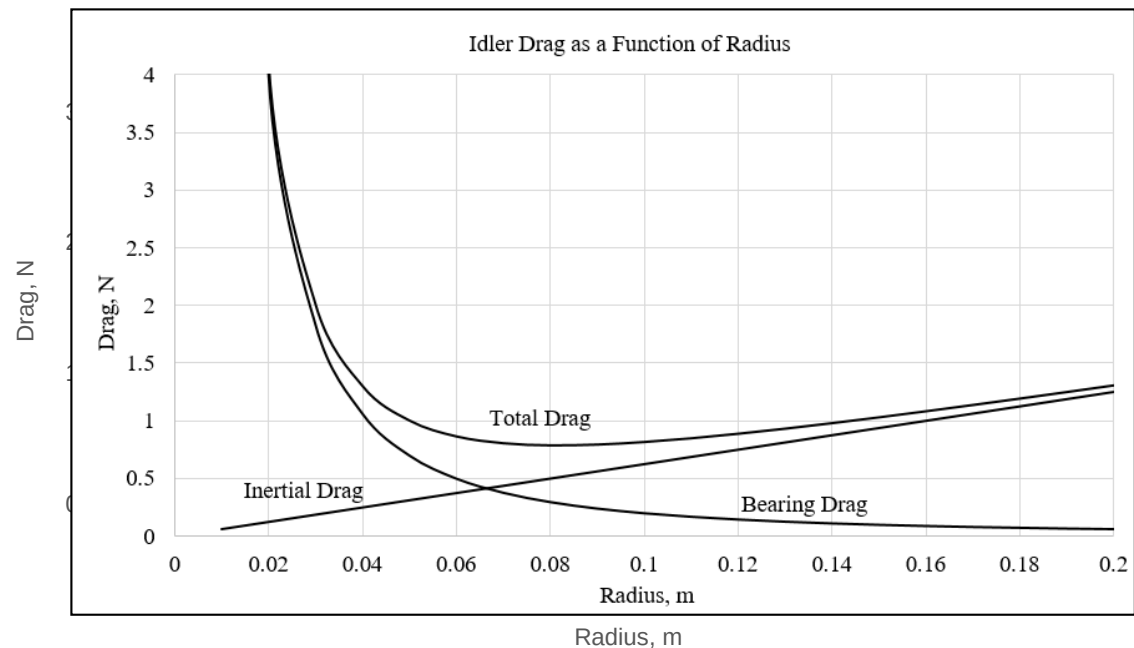
$$\Delta T_i = \pi (r_o^2 - (r_o - w)^2) l \rho A$$

COMBINING

- Combining bearing drag and inertial drag

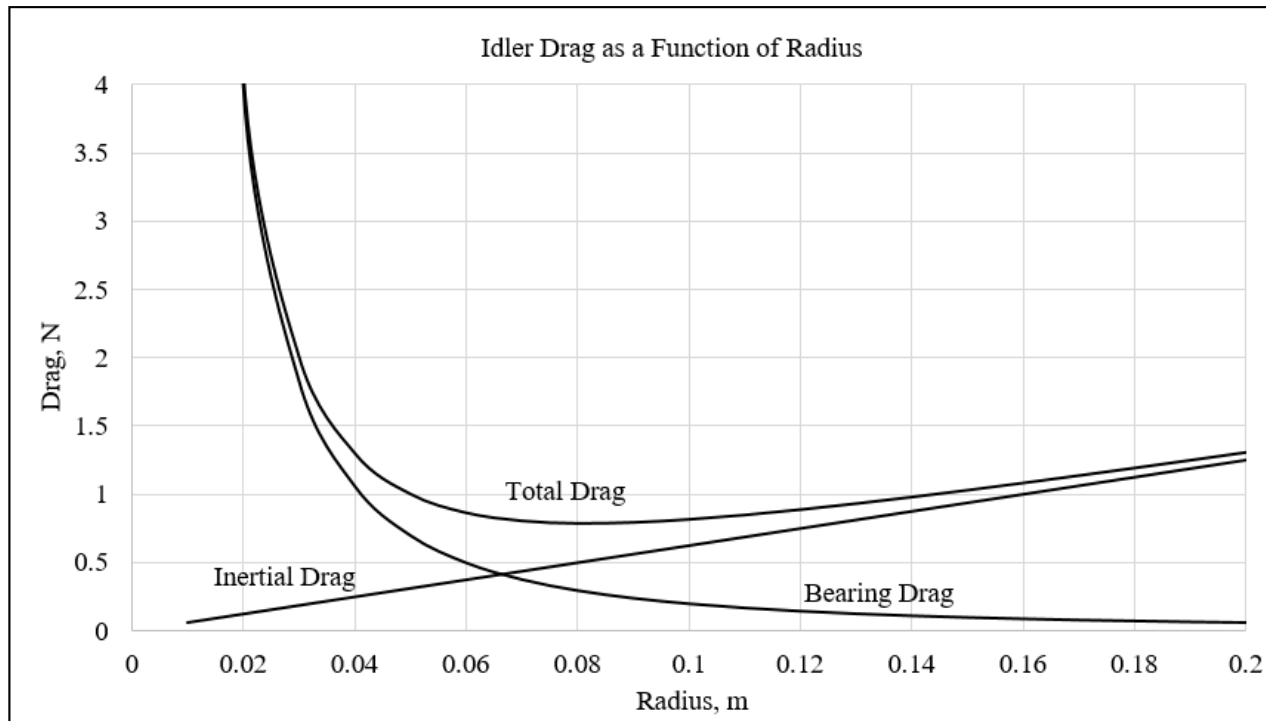
$$\Delta T = \tau/r_o + \gamma V/r_o^2 + \pi(r_o^2 - (r_o - w)^2) l \rho A$$

- Plotting total drag vs. radius



COMBINING

- The lowest total drag of 0.79 N occurs at 0.082 m.

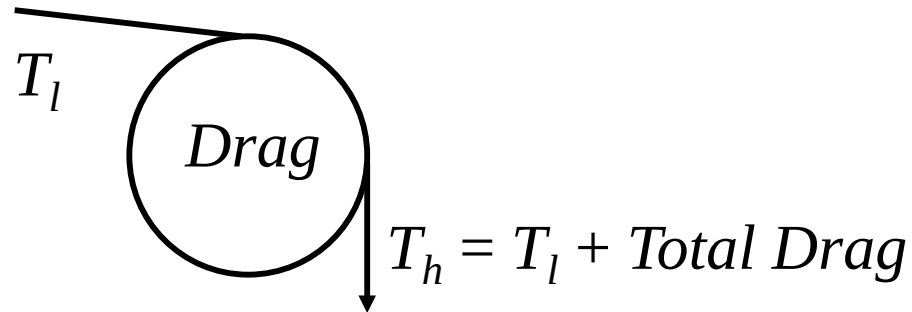


VALUES FOR THE EXAMPLE IDLER

$l =$	1	meters	idler shell length
$w =$	0.0025	meters	shell wall thickness
$\rho =$	1600	kg/m ³	material density
$A =$	0.25	m/sec ²	linear acceleration
$V =$	5	m/sec	linear velocity
$\alpha =$	0.005	N-m	bearing static drag
$\gamma =$	0.0003	(N-m)/sec	bearing viscous drag
$P =$	50	N/m	resultant web load
$k =$	9.87		SI natural freq const
$E =$	7.00E+10	N/m ²	Young's modulus of shell

Table 1 - Typical idler values for a generic carbon composite idler

MINIMUM TENSION

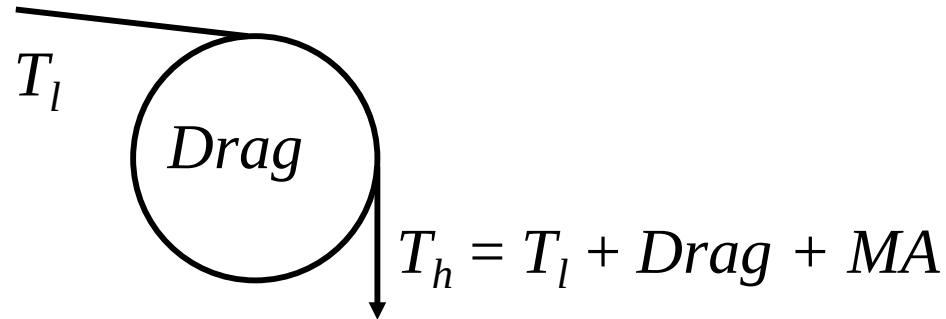


- Lower Tension Failure Limit

- Loss of traction with idlers defines a lower tension limit.

$$T_l > \frac{\text{Total Drag}}{e^{\mu\theta} - 1}$$

MINIMUM TENSION

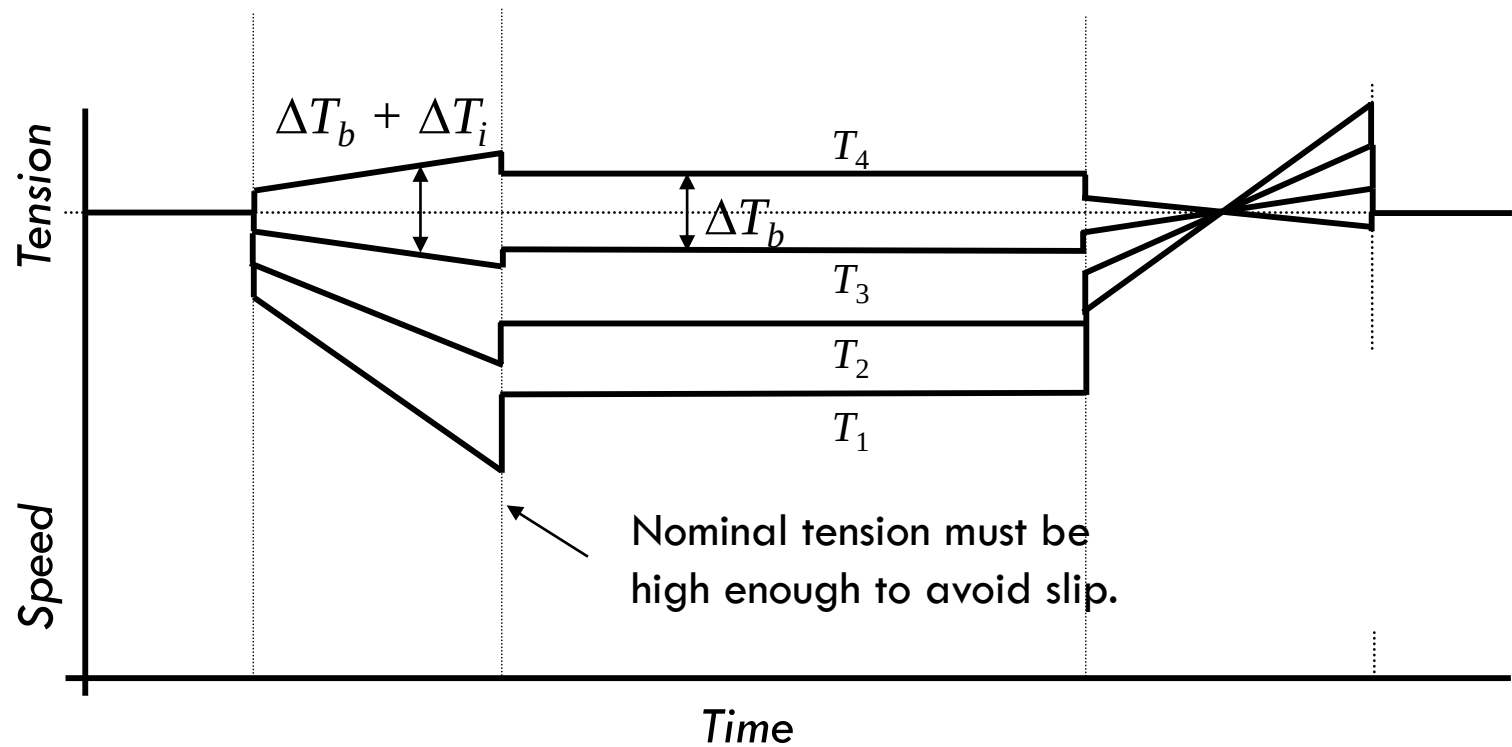


■ Lower Tension Failure Limit

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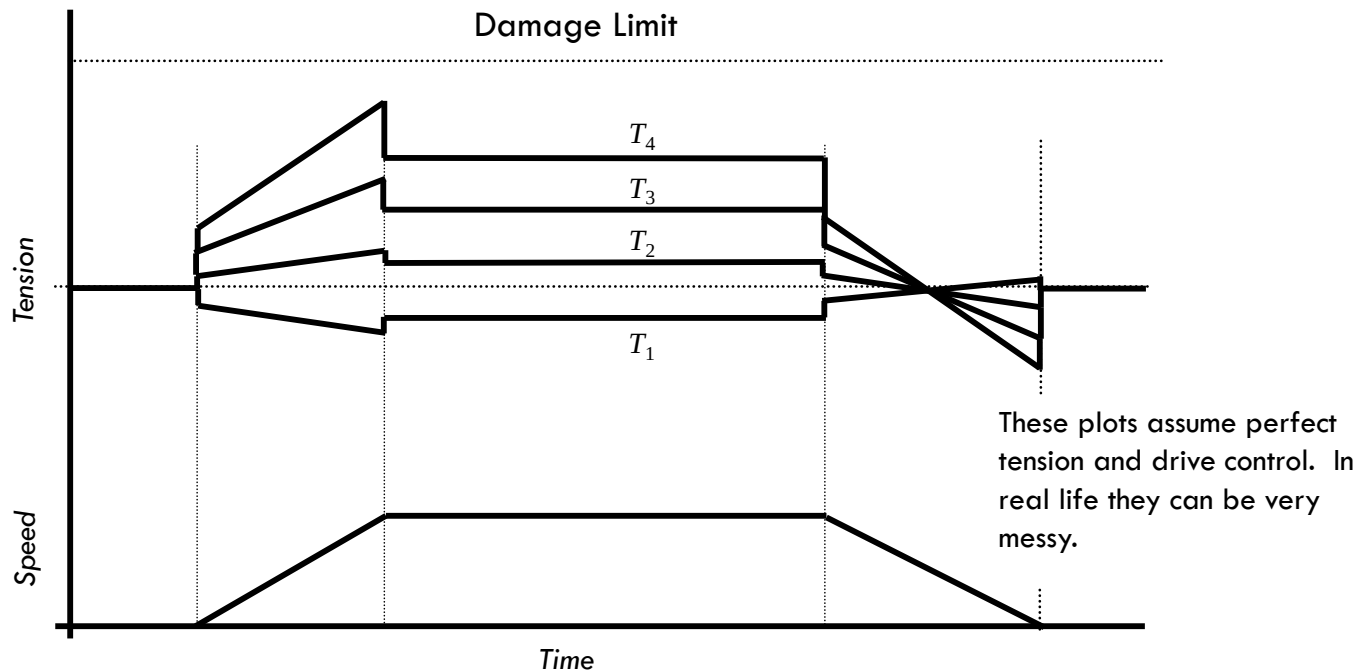
$$T_l > \frac{\tau/r_o + \gamma W/r_o^2 + \pi (r_o^2 - (r_o - w)^2) l r A}{e^{\mu\theta} - 1}$$

MINIMUM TENSION



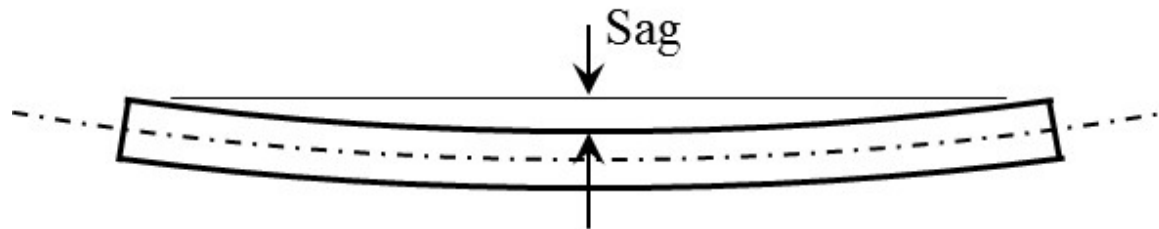
MAXIMUM TENSION

- Nominal tension must keep the peaks below the damage limit for the web.



DEFLECTION-SAG

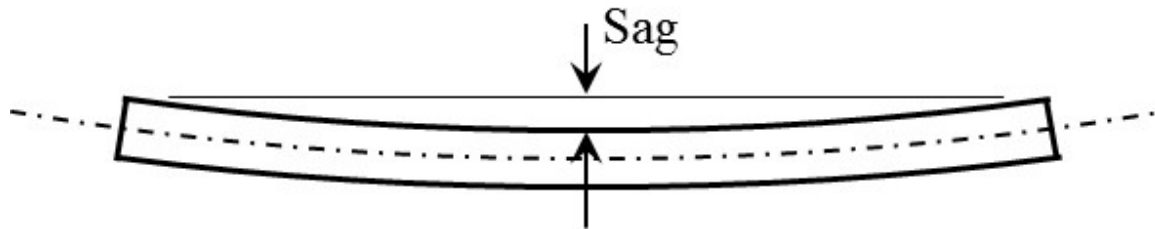
- Sag of the shell is important for a symmetrically and simply supported hollow shell idler.



$$\text{Sag} = 5Pl^4/(384EI) \quad \text{and} \quad I = \pi(r_o^4 - r_i^4)/4$$

DEFLECTION-SAG

- For an acceptable mid-point sag of 0.00015 m/m, any shell greater than 0.045 m is acceptable.



Radius, m	0.04	0.045	0.05	0.055	0.06	0.065	0.07	0.075	0.08	0.085
Sag, m	0.000201	0.000139	0.000101	0.000075	0.000058	0.000045	0.000036	0.000029	0.000024	0.000020

DEFLECTION-SAG

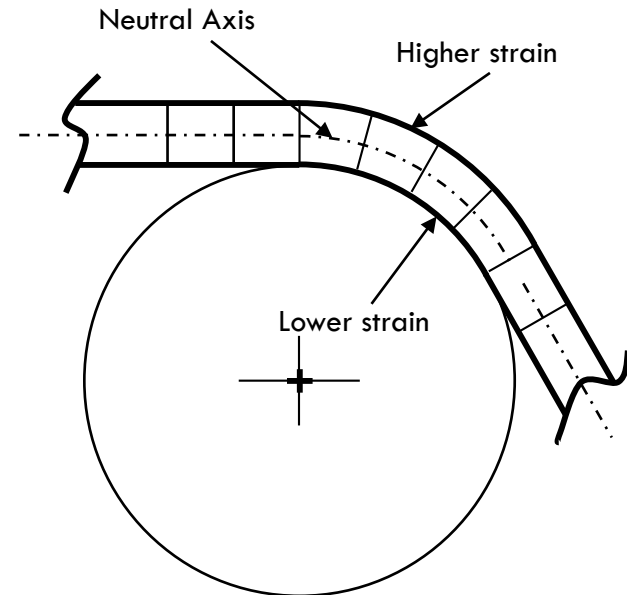
- A 0.045 m radius idler designed as in Table 1 will have 1.13 N of total drag; 40% more total drag than the 0.79 N of a similarly designed idler with 0.082 m radius.
- Its steady state drag will be 0.85 N vs. 0.28 N for the optimum idler diameter; 300% higher.
- Smaller is not always better!

BENDING RADIUS OF WEB

- Bending strain can damage the web in extension or compression.

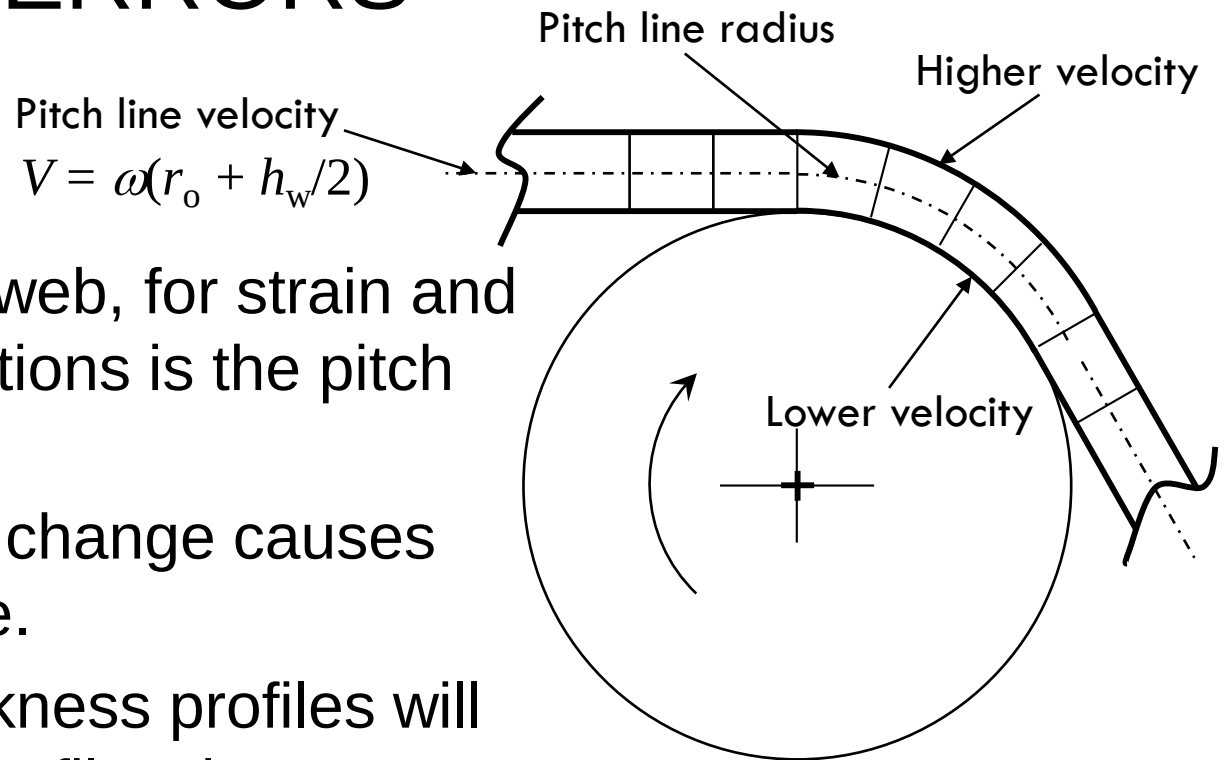
$$\Delta\epsilon \approx h_w/r_o$$

- Can be a factor for thick webs.



VELOCITY ERRORS

- Velocity of the web, for strain and tension calculations is the pitch line velocity.
$$V = \omega(r_o + h_w/2)$$
- Web thickness change causes velocity change.
- Webs with thickness profiles will have velocity profiles that can cause wrinkles and off tracking.
- Larger radius minimizes both affects.



OTHER FACTORS

- Air entrainment

$$h_a = 0.643r_o \left[\frac{6\eta(V_{\text{web}} + V_{\text{roller}})}{T/l} \right]^{2/3}$$

- Critical speed vs. RPM
- Dent resistance
- Standard size materials
- Machine size
- \$\$

$$\omega_c = \frac{k}{2\pi d^2} \sqrt{\frac{lEI}{m}}$$



QUESTIONS?

Thank You

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